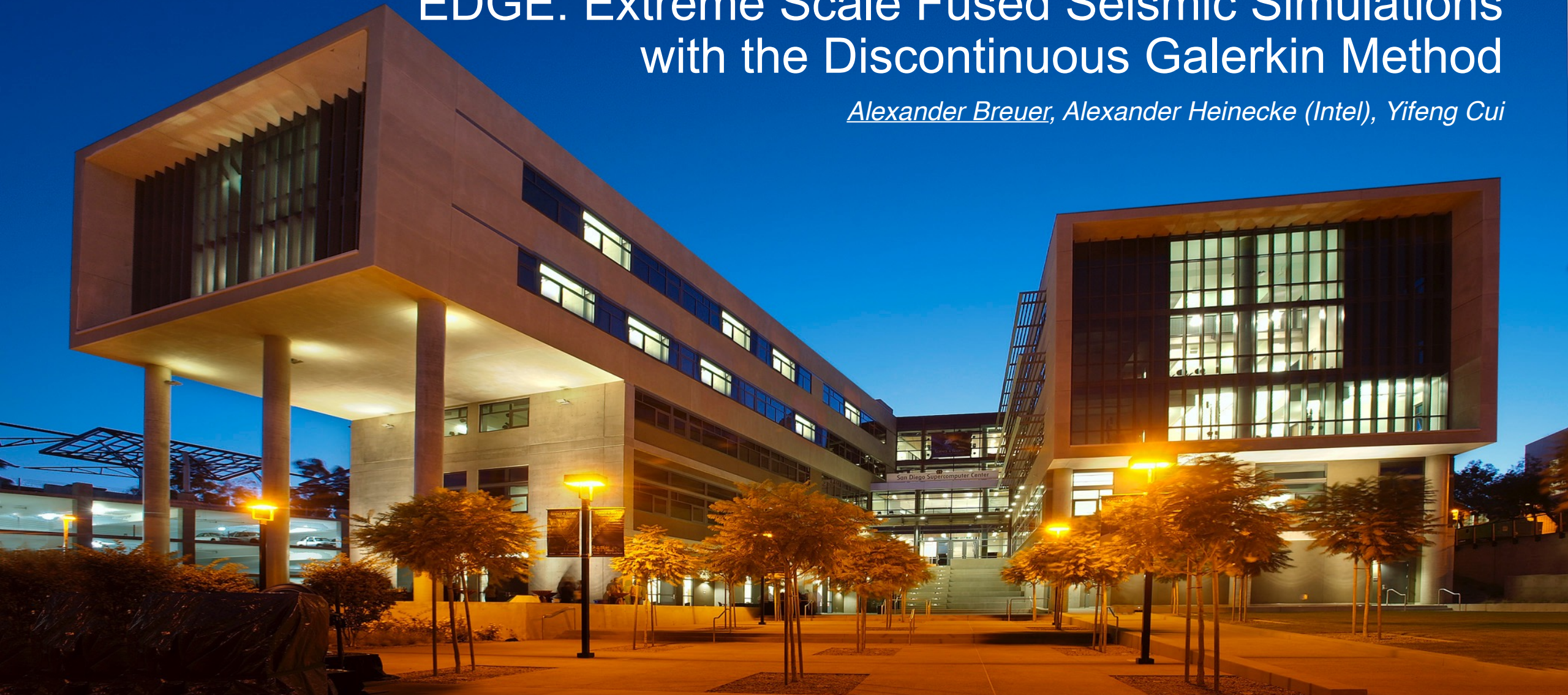


EDGE: Extreme Scale Fused Seismic Simulations with the Discontinuous Galerkin Method

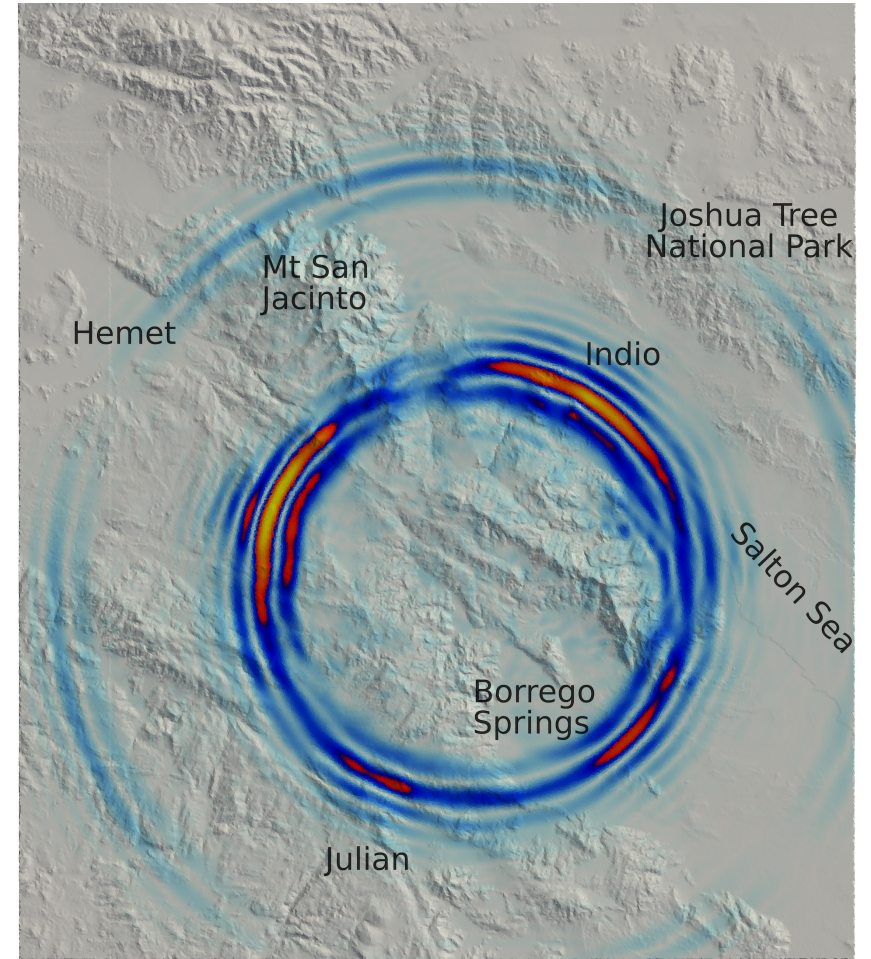
Alexander Breuer, Alexander Heinecke (Intel), Yifeng Cui



What is EDGE?

- **E**xtrême-scale **D**iscontinuous **G**alerkin **E**nvironment (EDGE): Seismic wave propagation through DG-FEM
- **Focus:** Problem settings with high geometric complexity, e.g., mountain topography
- **Written from scratch** to support fused forward simulations
- “**License**”: BSD 3-Clause (software), CC0 for supporting files (e.g., user guide)

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Example of hypothetical seismic wave propagation with mountain topography using EDGE. Shown is the surface of the computational domain covering the San Jacinto fault zone between Anza and Borrego Springs in California. Colors denote the amplitude of the particle velocity, where warmer colors correspond to higher amplitudes.

Getting Started: Advection Equation

- “Simplest” hyperbolic Partial Differential Equation (PDE)
- Elastic wave equations similar: Linear system with variable coefficients

$$q(x, t)_t + v \cdot q(x, t)_x = 0, v \in \mathbb{R}$$

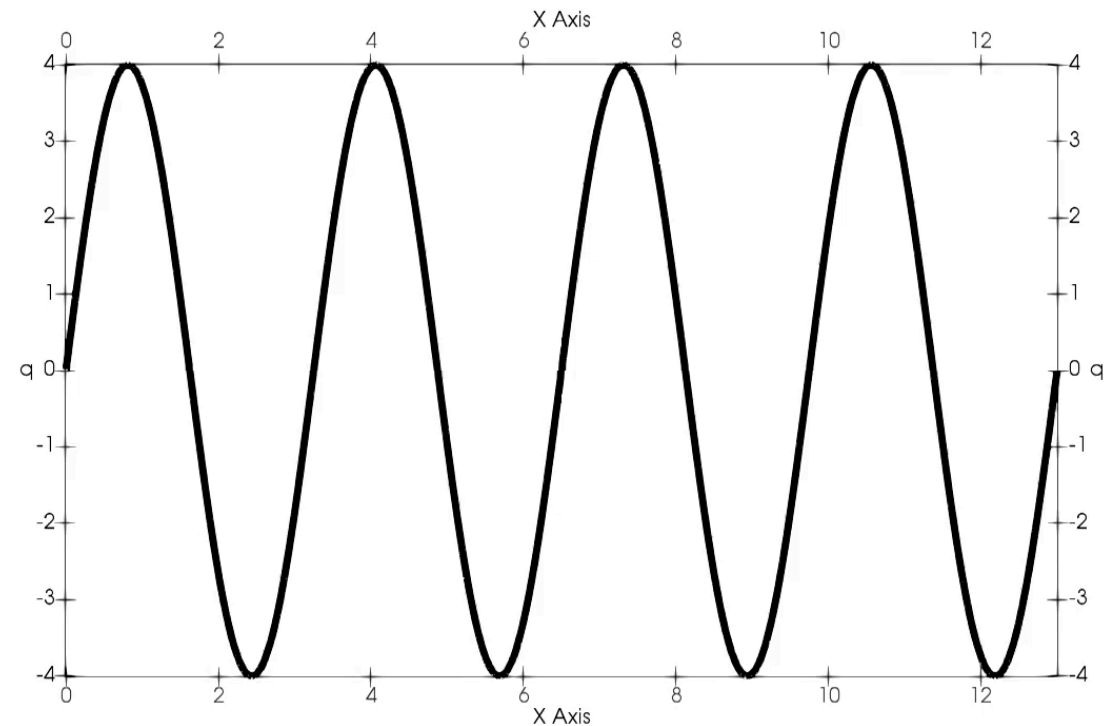


Illustration of EDGE's non-fused, third order (P2 elements) ADER-DG solver applied to the advection equation with sinusoidal initial values and periodic boundary conditions.

Getting Started: Fused Solver

- **Non-Fused:** $o = s(i)$
 $o_1 = s(i_1) \quad o_4 = s(i_4)$
 $o_3 = s(i_3) \quad o_2 = s(i_2)$
- **Fused:** $O_m = S_m(I_m)$
 $O_4 = (o_1, o_2, o_3, o_4) = S_4(I_4)$
 $= S_4(i_1, i_2, i_3, i_4)$

$$q(x, t)_t + v \cdot q(x, t)_x = 0, \quad v \in \mathbb{R}$$

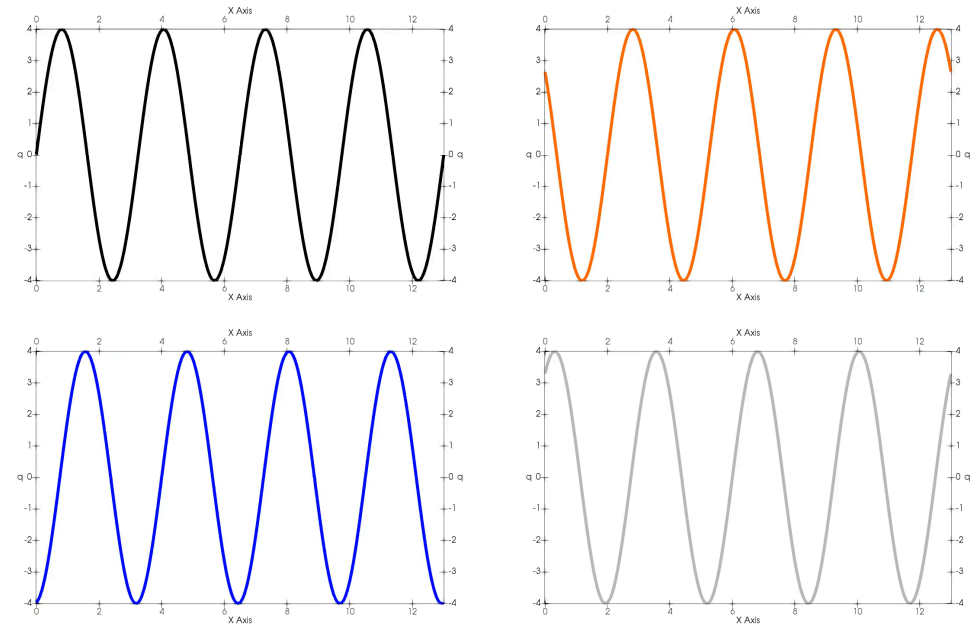


Illustration of EDGE's non-fused, third order (P2 elements) ADER-DG solver applied to the advection equation for four problem settings with sinusoidal initial values and periodic boundary conditions.

Getting Started: Fused Solver

- **Non-Fused:** $o = s(i)$
 $o_1 = s(i_1) \quad o_4 = s(i_4)$
 $o_3 = s(i_3) \quad o_2 = s(i_2)$
- **Fused:** $O_m = S_m(I_m)$
 $O_4 = (o_1, o_2, o_3, o_4) = S_4(I_4)$
 $= S_4(i_1, i_2, i_3, i_4)$

$$q(x, t)_t + v \cdot q(x, t)_x = 0, \quad v \in \mathbb{R}$$

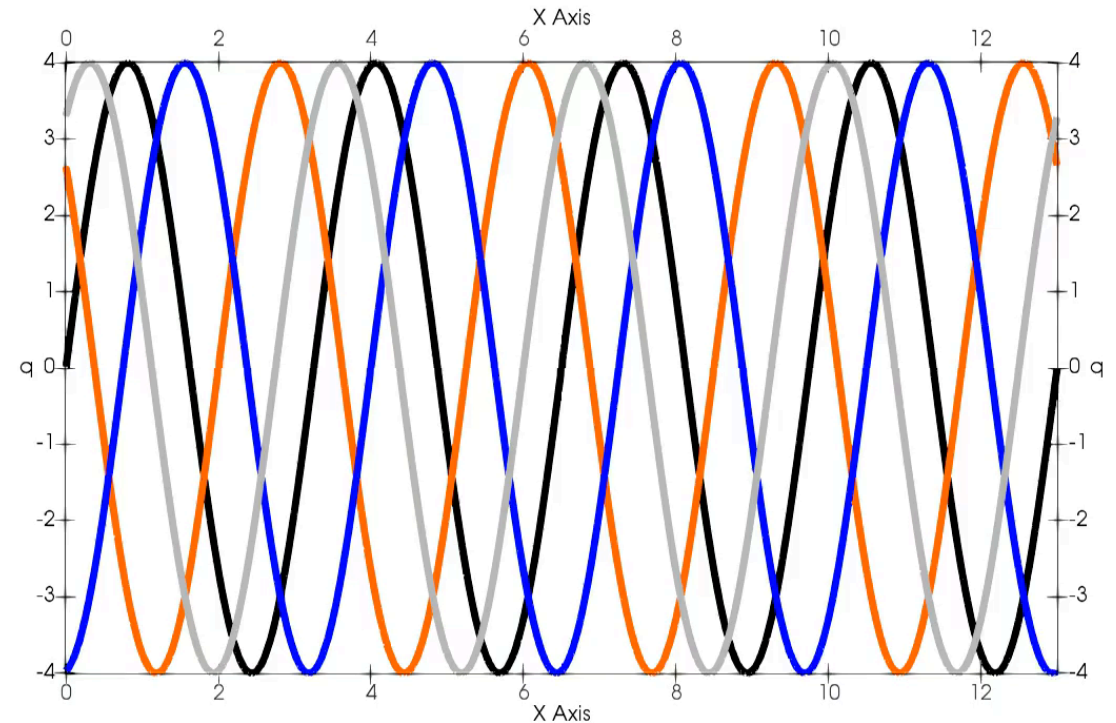


Illustration of EDGE's fused (4 simulations), third order (P2 elements) ADER-DG solver applied to the advection equation with sinusoidal initial values and periodic boundary conditions.

DOFs: Non-Fused vs. Fused

$$o = s(i)$$

$$O_4 = S_4(I_4)$$

Diagram illustrating the memory layout for a single quantity (non-fused).

The layout is a 3x3 grid of elements, indexed by modes (0, 1, 2) on the vertical axis and elements (0, 1, 2) on the horizontal axis. The values are:

0	0	3	6
1	1	4	7
2	2	5	8

Diagram illustrating the memory layout for 4 fused simulations.

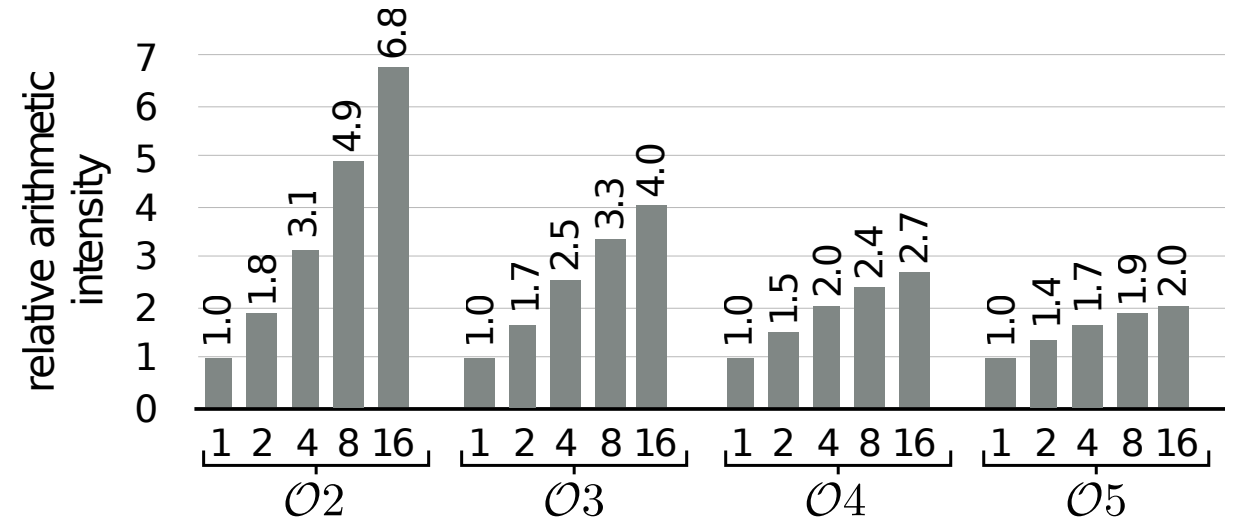
The layout is a 3x12 grid of elements, indexed by modes (0, 1, 2) on the vertical axis and elements (0, 1, 2, 3) on the horizontal axis. The layout is divided into three sections, each labeled "fused runs" above the element indices. The values are:

	fused runs				fused runs				fused runs			
	0	1	2	3	0	1	2	3	0	1	2	3
0	0	1	2	3	12	13	14	15	24	25	26	27
1	4	5	6	7	16	17	18	19	28	29	30	31
2	8	9	10	11	20	21	22	23	32	33	34	35

Illustration of the memory layout for EDGE's third order ADER-DG solver, line elements, and the advection equation (single quantity). Left: Non-fused memory layout, right: memory layout for 4 fused simulations.

Key Advantages

- Full vector operations, even for sparse matrix operators
- Automatic memory alignment
- Read-only data shared among all runs
- Lower sensitivity to latency (memory & network)



Relative arithmetic intensities. Shown are convergence rates 2-5 for the fusion of 2,4,8,16 simulations vs. a non-fused simulation for the elastic wave equations, using an ADER-DG solver. [ISC17]

“Similar Enough”: EDGE’s Approach

1. Identical mesh for all fused simulations
2. Identical simulations parameters:
 1. Start and end time
 2. Convergence rate
 3. “Frequency” of wave field output, “frequency” and location of seismic receivers
3. Identical material parameters (velocity model)
4. “Sources”:
 1. Arbitrary initial DOFs
 2. Kinematic sources: Fused or non-fused point sources
 3. Spontaneous rupture: Identical friction law, other parameters (e.g., nucleation, initial stresses, coefficients) arbitrary

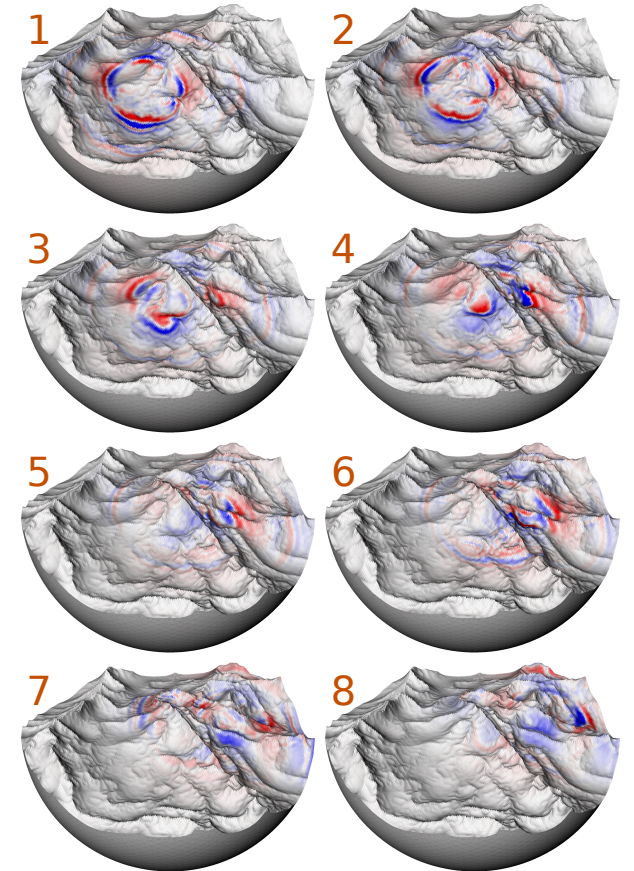
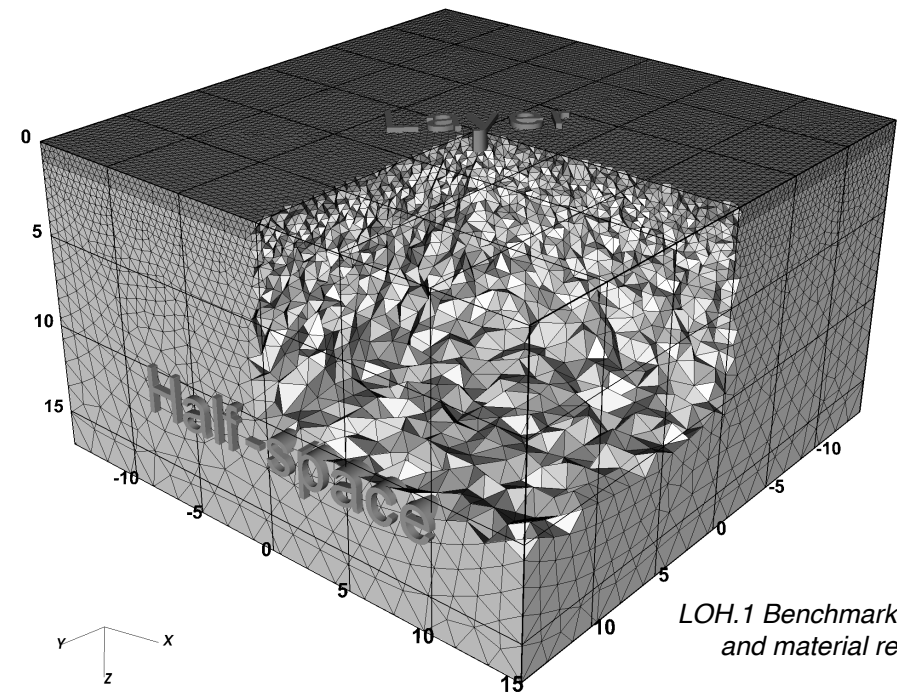


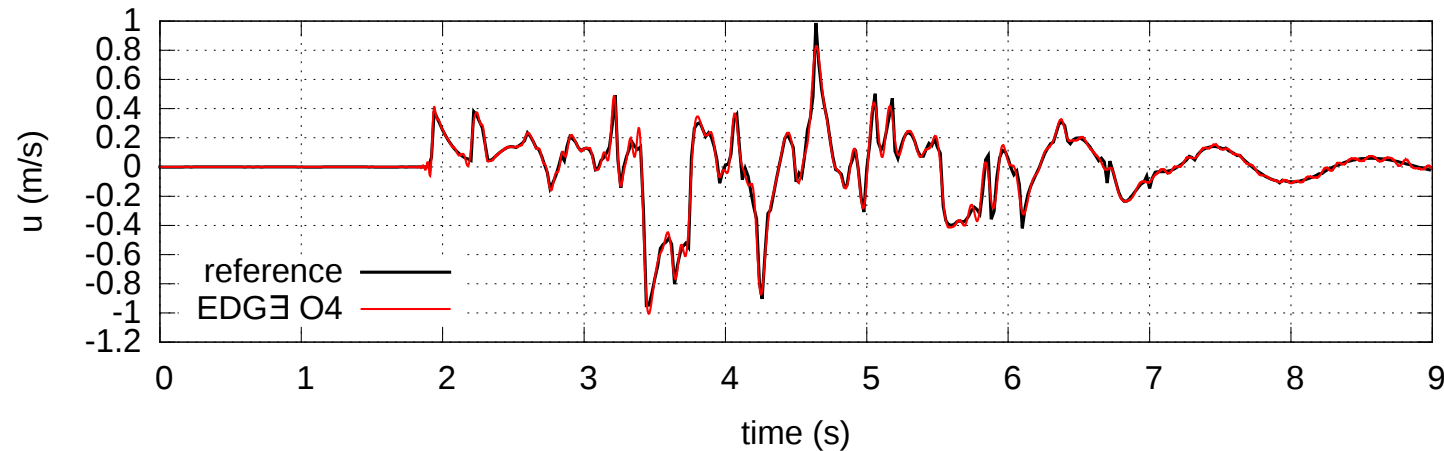
Illustration of the wave field for an exemplary fusion of eight simulations in EDGE with eight point sources at different locations.

Performance: LOH.1

- **Layer Over Halfspace (LOH.1):**
Benchmark used for code verification
- **Orders: 2-6 (non-fused), 2-4 (fused)**
- **Unstructured tetrahedral mesh:**
350,264 elements
- **Single node of Cori-II (68 core Intel Xeon Phi x200, code-named Knights Landing)**
- **EDGE vs. SeisSol (GTS, git-tag 201511)**

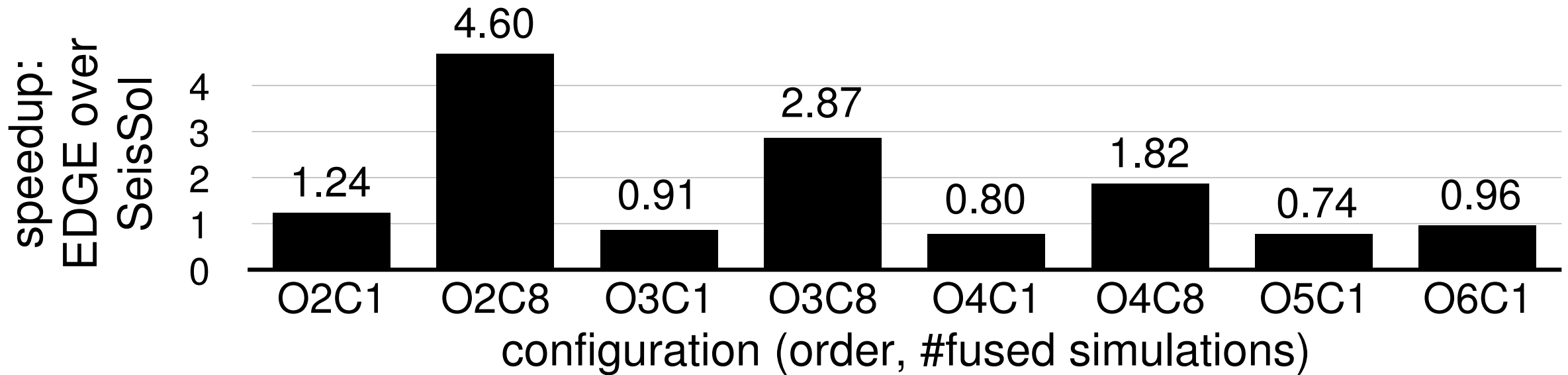


LOH.1 Benchmark: Example mesh and material regions [ISC16_1]



Synthetic seismogram of EDGE for quantity u at the ninth seismic receiver located at (8647 m, 5764 m, 0) in red. The reference solution is shown in black. Detailed setup: [ISC17]

Fused Simulations: Speedup



Speedup of EDGE over SeisSol (GTS, git-tag 201511). Convergence rates O2 – O6: single non-fused forward simulations (O2C1-O6C1). Additionally, per-simulation speedups for orders O2–O4 when using EDGE's full capabilities by fusing eight simulations (O2C8-O4C8). [ISC17]

Weak: Setup

- Regular cubic mesh, 5 Tets per Cube, 4th order (P3) and 6th order (P5)
- Imitates convergence benchmark
- 276K elements per node
- 1-9000 nodes of Cori-II (9000 nodes = 612,000 cores)

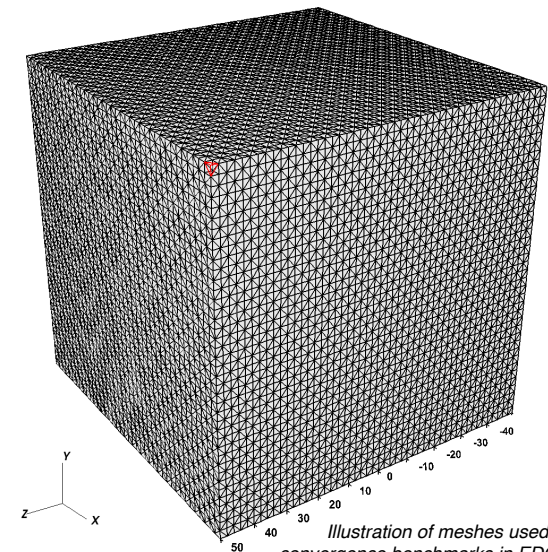
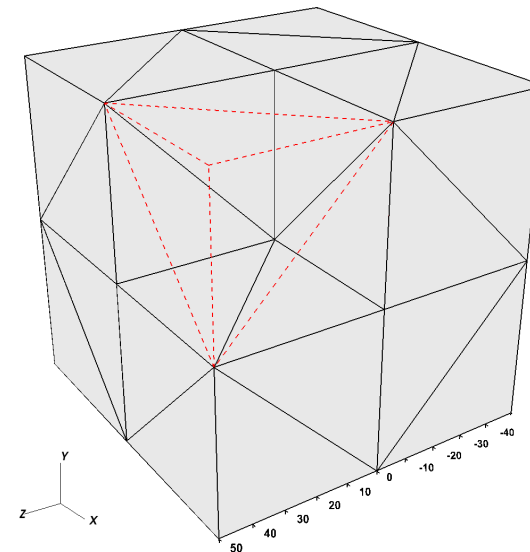
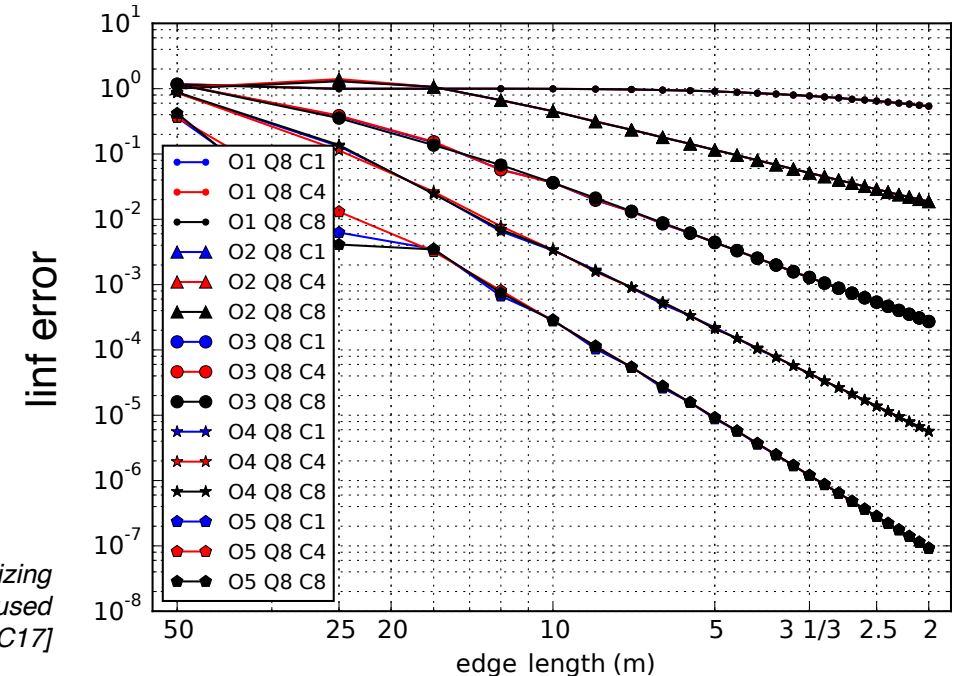


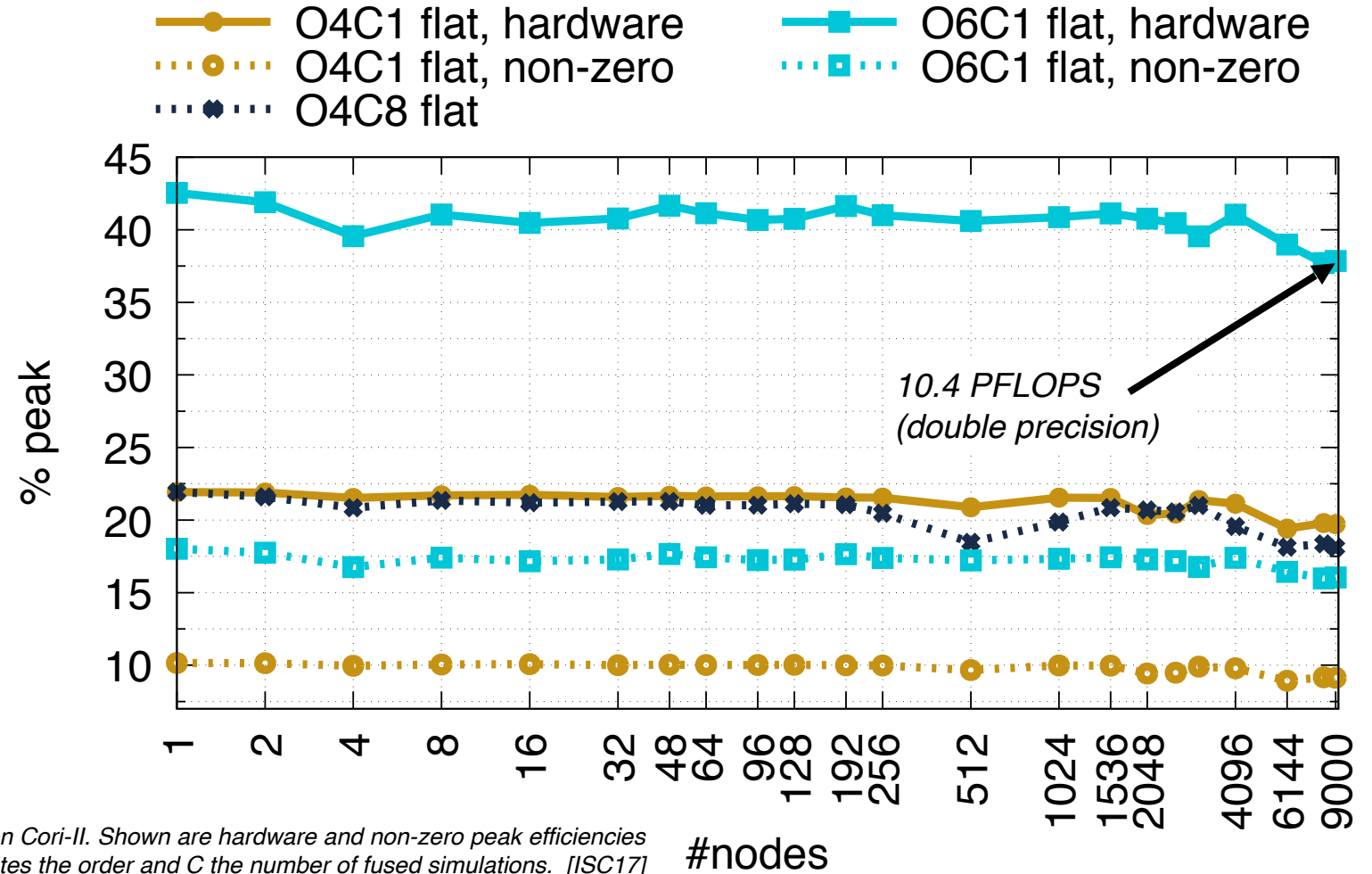
Illustration of meshes used for convergence benchmarks in EDGE.



Convergence of EDGE in the L^∞ -norm. Shown are orders O1 – O5 for quantity v (Q8) when utilizing EDGE's fusion capabilities with shifted initial conditions. For clarity, from the total of eight fused simulations, only errors of the first (C1), fourth (C4) and last simulation (C8) are shown. [ISC17]

Weak: Results

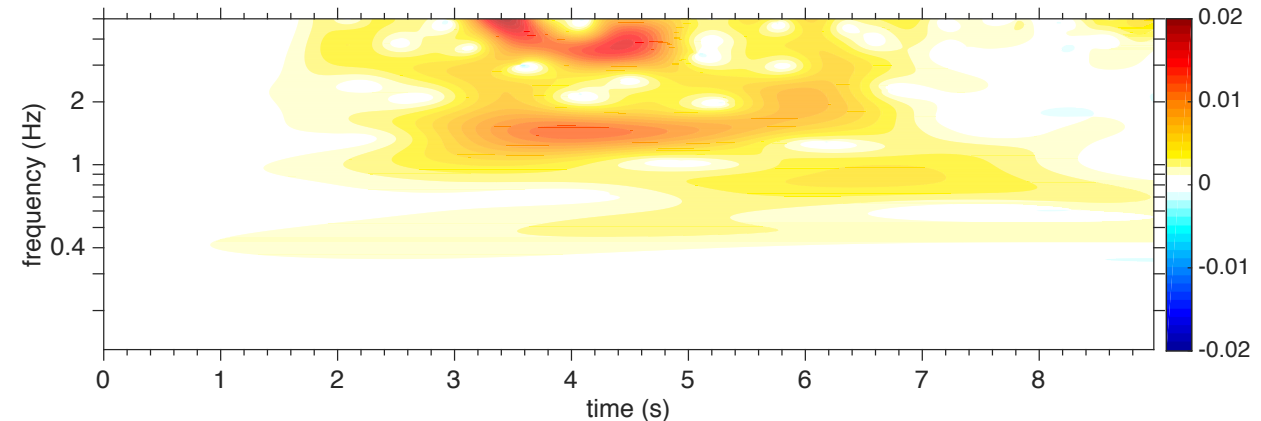
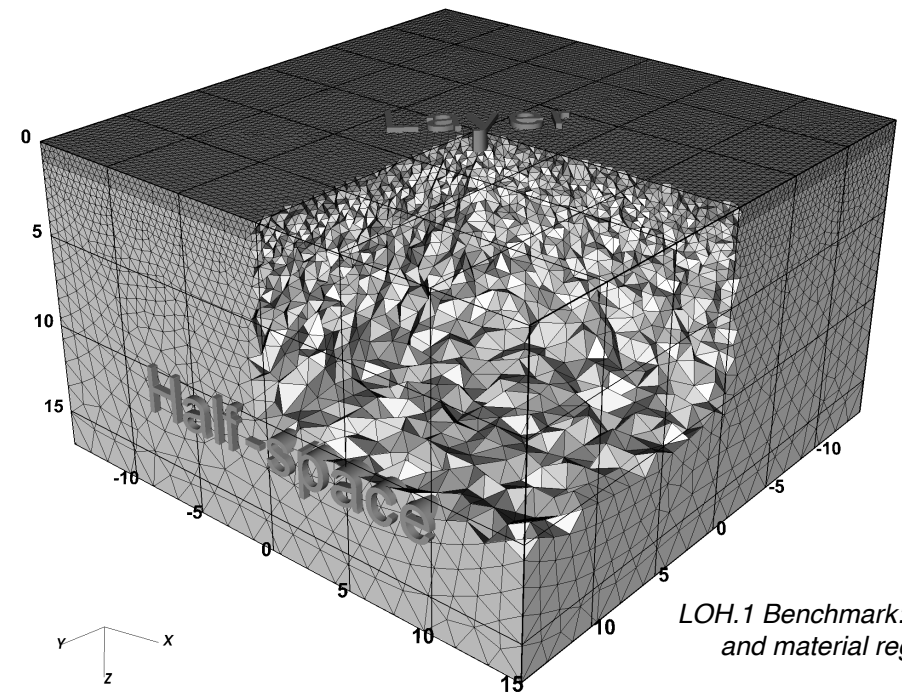
- **O6C1 @ 9K nodes:**
10.4 PFLOPS (38% of peak)
- **O4C8 vs. O4C1 @ 9K nodes:**
2.0x speedup



Weak scaling study on Cori-II. Shown are hardware and non-zero peak efficiencies in flat mode. O denotes the order and C the number of fused simulations. [ISC17]

Strong: LOH.1

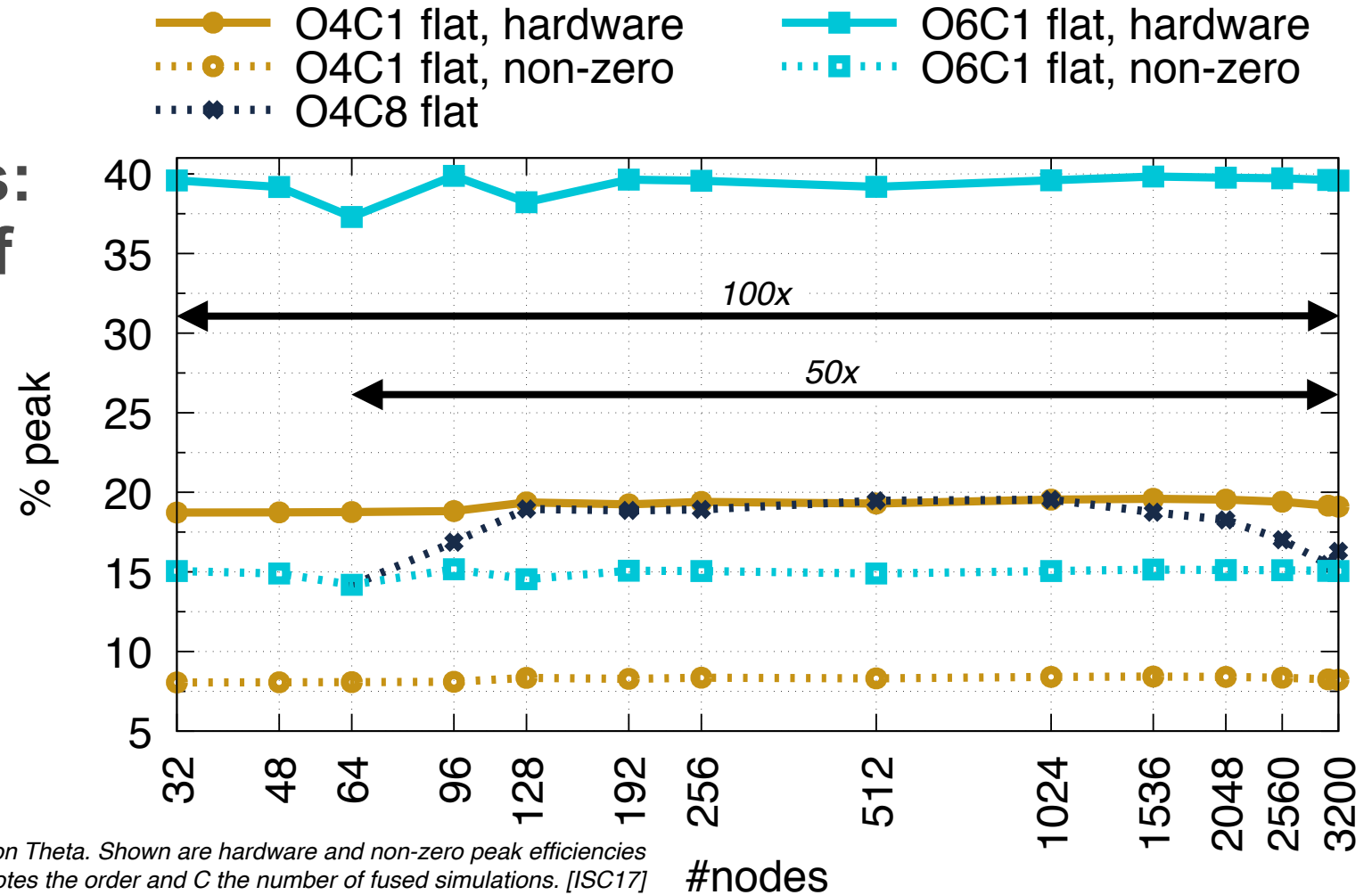
- Orders: 4 & 6 (non-fused), 4 (fused)
- Unstructured tetrahedral mesh: 172,386,915 elements
- 32-3200 nodes of Theta (64 core Intel Xeon Phi x200, code-named Knights Landing)
- 3200 nodes = 204,800 cores



Time-frequency misfit for quantity u at the ninth seismic receiver located at (8647 m, 5764 m, 0) and in a frequency range between 0.13Hz and 5Hz. Detailed setup: [ISC17], Visualization: TF-MISFIT_GOF_CRITERIA, <http://nuquake.eu>

Strong: Results

- O6C1 @ 3.2K nodes:
3.4 PFLOPS (40% of peak)
- O4C8 vs. O4C1 @
3.2K nodes:
2.0x speedup



Strong scaling study on Theta. Shown are hardware and non-zero peak efficiencies in flat mode. O denotes the order and C the number of fused simulations. [ISC17]

EDGE: Current and Upcoming

- Elements: Line, rectangular quads, 3-node triangles, rectangular hexes, 4-node tets
- Equations: Advection (FV+ADER-DG: 1D, 2D, 3D), Shallow Water (FV: 1D), Elastic Wave Equations (FV+ADER-DG: 2D, 3D)
- Parallelization: Assembly kernels for WSM, SNB, HSW, KNC (non-fused), KNL (fused & non-fused), OpenMP (custom), MPI (overlapping)
- Continuity: Continuous Integration (sanity checks), Continuous Delivery incl. automated convergence + benchmarks runs, automated code coverage, automated license checks, container bootstrap
- “License”: BSD 3-Clause (software), CC0 for supporting files (e.g., user guide)



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- Sparse, fused assembly kernels for orders 5+ (✓)
- Kinematic Sources (Standard Rupture Format): Support for fused and non-fused source (✓) descriptions
- Spontaneous Rupture Simulations (✓)
- Grouped Local Time Stepping
- EDGEcut: Automated surface and volume meshing

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EDGE heavily relies on contributions of many authors to open-source software.

This software includes, but is not limited to: **ASan** (<https://clang.llvm.org/docs/AddressSanitizer.html>, debugging), **Catch** (<https://github.com/philsquared/Catch>, unit tests), **CGAL** (<http://www.cgal.org>, surface meshes), **Clang** (<https://clang.llvm.org/>, compilation), **Cppcheck** (<http://cppcheck.sourceforge.net/>, static code analysis), **Easylogging++** (<https://github.com/easylogging/>, logging), **GCC** (<https://gcc.gnu.org/>, compilation), **gitbook** (<https://github.com/GitbookIO/gitbook>, documentation), **Gmsh** (<http://gmsh.info/>, volume meshing), **GoCD** (<https://www.gocd.io/>, continuous delivery), **jekyll** (<https://jekyllrb.com>, homepage), **libxsmm** (<https://github.com/hfp/libxsmm>, matrix kernels), **MOAB** (<http://sigma.mcs.anl.gov/moab-library/>, mesh interface), **ParaView** (<http://www.paraview.org/>, visualization), **pugixml** (<http://pugixml.org/>, XML interface), **SCons** (<http://scons.org/>, build scripts), **Valgrind** (<http://valgrind.org/>, memory debugging), **Visit** (<https://wci.llnl.gov/simulation/computer-codes/visit>, visualization).